

sc2 Reference Manual

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Abstract

sc2 is a new implementation of the Streams-C[3] language and compiler. This manual describes the Streams-C language and sc2 compiler structure. The Streams-C programming model is that of communicating processes. A system consists of a collection of processes that communicate using streams and signals. Processes can run either in software on conventional processors (SP) or in hardware on FPGA processors (HP). Processes (and their associated stream and signals) can be created dynamically by other software processes.

The sc2 compiler, which consists of several passes using the Stanford University Intermediate Format (SUIF) infrastructure, is used to compile FPGA processes. The compiler translates a subset of C into Register-Transfer-Level (RTL) VHDL that is synthesizable on FPGAs.

The sc2 compiler passes are freely available for noncommercial use in source form from Los Alamos National Laboratory. Please contact the authors for more information.

1. Introduction

This manual describes the Streams-C language and compiler. sc2 is a new implementation of Streams-C [3], a parallel language following the communicating processes model. The language consists of a small collection of additions to C in the form of new data types and intrinsic calls. The sc2 compiler translates the C program into Register-Transfer-Level (RTL) VHDL that can be synthesized to FPGAs.

In the manual we describe the language extensions, define the subset of C that we can translate to VHDL, and sketch the compiler implementation. sc2 defines *processes* that communicate data over *streams* and events via *signals*. A process may be a software process (SP) on a conventional processor or a hardware process (HP) on an FPGA. The sc2 compiler is used to translate HP processes to VHDL. SP processes, which use a software library included with sc2, are compiled by the native C compiler of the system.

The original Streams-C compiler targeted the Annapolis MicroSystems Wildforce FPGA board. The sc2 compiler release provides hardware libraries for the AMS Firebird, which contains a single Xilinx Virtex 2 on a 64-bit PCI bus. The sc2 software library is based on Linux.

1.1. Scope of this Reference Manual

The purpose of this reference manual is to present the unique features of Streams-C, along with examples of its use. This reference guide is *not* intended to be a reference on the ANSI C programming language¹. Also, it is assumed that the reader is familiar with parallel programming and the communicating process model².

¹See for example ref to ansi c.

²ref to MPI etc.

1.2. Conventions

All C syntax conventions are followed for Streams-C. The code appearing in the body of a Streams-C process does not introduce any non-C syntax. New constructs appear in the form of predefined types and intrinsic functions and in directives (in comment blocks) to the sc2 compiler.

Whenever a Streams-C construct – predefined type, intrinsic function, etc. is referenced – it will be shown in **bold face**, with all C and user-supplied information interspersed in the construct in regular type. All sc2 predefined types and intrinsic functions have the preface **sc_** as part of their name.

An explanation of language features that are restricted in the current implementation of the compiler are identified by ‘(I)’ preceding or following the manual text, as appropriate. Examples of *illegal code* are preceded by an *italic* warning stating that the example is illegal.

A loose BNF notation is used to describe syntax. When a category in angle brackets contains the string “name,” it must be a C identifier, eg. <stream_name> denotes the name of a stream, and the name must conform to C identifier format.

2. Programming Model

The concept of using Field Programmable Gate Arrays (FPGAs) as customizable compute engines began in the late 1980’s, and since then, many realizations of that concept have been developed that have delivered the promised performance acceleration. However, that 10x-100x of performance that can be obtained for suitable applications on Reconfigurable Computers (RCCs) has been at the cost of 10x-100x increase in difficulty of application development. FPGA-based systems offer the programmability of software, allowing a vast number of applications and application variants to be mapped onto them. Despite many promising research efforts, the mainstream of application development must use Computer-Aided Design (CAD) tools that are oriented towards hardware rather than software development, characterized by high cost of the tool set, long compile times if a reasonable level of abstraction and portability are desired, and most important, the necessity of developing and completely understanding the cycle-by-cycle behavior of millions of gates spanning multiple FPGA chips and fixed function units.

In recent years, a concerted effort has been launched to remedy the design tool problem. Many of these tools are embedded in high level design simulation environments (Ptolemy, Khoros, MatLab, Handel C)([7], [8]) or target “dusty deck” sequential procedural code ([4]), while others target low level, technology-specific, optimized designs ([1], [6]).

The sc2 language represents an intermediate approach between those very high level and very low level design tools. Our target machine is an attached parallel processor such as the Annapolis Microsystems Wildforce, the ISI SLAAC, or the Los Alamos National Laboratories (LANL) RCA-2 boards. These PCI or VME accelerators sit on the I/O bus of a conventional workstation or PC. They include multiple FPGAs interconnected by both fixed and programmable resources. The FPGAs have access to local or shared SRAM chips, and have some relatively slow method of communicating with the workstation.

With current compiler technology, parallelization of the application and mapping to the FPGA board architecture are best performed by the application developer. This is in keeping with methods of programming conventional parallel machines, in which the application developer usually manually parallelizes the program and inserts message-passing and synchronization logic. However, it is our thesis that the application developer should not have to be a hardware designer in order to develop reasonably efficient programs, that clock-cycle-level of specification should not be required. With this middle approach, software engineers knowledgeable in parallel programming can create applications on FPGA-based processors.

The sc2 model embodies the above design goals. Our programming model is targeted at stream-oriented FPGA applications. Characteristics of stream-oriented computing include high-data-rate flow of one or more data sources; fixed size, small stream payload (one byte to one word); compute-intensive operations, usually low precision fixed point, on the data stream; access to small local memories holding coefficients and other constants; and occasional synchronization between computational phases.

The sc2 language is actually a small set of annotations and library functions callable from a conventional C program. The annotations are used to declare a **process**, **stream**, or **signal**, and to assign resources on the FPGA board to those objects. The library functions are used to communicate stream data between the processes.

sc2 follows the Communicating Sequential Processes (CSP) [5] parallel programming model. The implementation is a combination of annotations and library functions callable from C. This is for pragmatic reasons as our compiler is built within the framework of the SUIF compiler infrastructure, which best supports C and Fortran. In our model, there are three distinguished objects, processes, streams, and signals. A process is an independently executing object with a process body (the “run function”) that is given by a C subroutine. A process can run on a conventional processor or on an FPGA chip. An

```

/// PROCESS_FUN <function_name>
/// IN_STREAM <stream_element_data_type_name> <stream_name>
... other input streams ...
/// OUT_STREAM <stream_element_data_type_name> <stream_name>
... other output streams ...
/// IN_SIGNAL <signal_element_data_type_name> <signal_name>
... other input signals ...
/// OUT_SIGNAL <signal_element_data_type_name> <signal_name>
... other output signals ...
/// PARAM <parameter_type_name> <parameter_name>
... other parameter declarations ...
/// PROCESS_FUN_BODY
... C code ...
/// PROCESS_FUN_END

```

Figure 1. Format of a Streams-C Run Function

FPGA process must be written in a subset of C (subset defined below in Section 6). In addition, intrinsic functions to perform stream or signal operations may be referenced. Processes may be initiated dynamically during execution. A process runs until it exits with a return statement, control reaches the end of the process body, or it is terminated by its initiating process.

The sc2 compiler synthesizes hardware circuits for one or more FPGAs as well as a set of communicating processes on conventional processors. The compiler includes previously reported features ([2]) extended to pipelined stream computation, so that the generated hardware/software is capable of pipelining a computation across multiple FPGAs and the conventional processor. Our system includes a functional simulation environment, allowing the programmer to simulate the collection of parallel processes and their communication at the functional level.

3. Declaring Processes, Streams, and Signals

3.1. Graphical Description

3.2. Textual Description

This section describes the format for describing the specific processes, streams, and signals that a Streams-C program uses. These directives are embedded in specially formatted blocks. Each directive must be on one line. Each directive is prepended by “//” starting with the first character of the line. Next, a keyword identifying the directive must appear, followed by parameter(s) to the directive.

The first set of directives describe the “run function” of a process. This is the body of code that gets executed when the associated process is initiated. The PROCESS_FUN directive gives a name to the run function, input and output stream and signal parameters, followed by an optional parameter to be passed to the process when it is initiated. After the parameter, the body of the function appears as normal C code, usually containing variable declarations, stream and/or signal communication, and computation. A keyword directive is used to mark the end of the run function.

The function name is a C identifier. The stream and signal names are also identifiers, and can be used within stream operations within the body of the C code. The data type of stream or signal elements precedes the name of the stream or signal as in normal C syntax. A single parameter to the process is also permitted. The format of the PROCESS_FUN directive is shown in Figure 1.

To describe a process to Streams-C, the PROCESS directive is used. A process has an associated run function and is of type “SP” (software process) or “HP” (hardware process). The PROCESS directive optionally may be used to declare a 1-dimensional array of processes.

The use of <array_spec> means that the system contains <integer> number of processes. Arrays of processes are often useful to describe systolic computation. The type of each process must be given as either SP for software process or HP for hardware process. If omitted, SP is assumed. The optional ON clause maps the process onto a specific resource of the system

```

/// PROCESS <process_name> [<array_spec>] PROCESS_FUN <process_fun_name>
    [TYPE [SP | HP]] <on_spec>
<array_spec> ::= '[' <integer> ']'
<on_spec>     ::= [ ON <resource_name> ]

```

Figure 2. Format of a Streams-C Process Directive

```

/// CONNECT <process_name> <process_ref1>.<port> [ <fifo_spec> ] \
    <process_name> <process_ref2>.<port> [ <fifo_spec> ]

<process_ref1> ::= '[' <integer> ']' |
                  '[' <integer> .. <integer> ']'

<process_ref2> ::= '[' <integer> ']' |
                  '[' '!' [+|-] <integer> ']'

<port>       ::= stream or signal name from a PROCESS_FUN directive

<fifo_spec>  ::= FIFO_SIZE <uint>

```

Figure 3. Format of a Streams-C CONNECT Directive

such as a specific FPGA chip or processor. The default for a software process is sc_host; default for hardware processes is FPGA. Figure 2 shows the format of the PROCESS directive.

The last directive CONNECT is used to connect processes via streams and signals. To connect two processes, the name of one process's stream or signal is associated with the name of another process's stream or signal. In Figure 3, the stream or signal formal parameter defined in the PROCESS_FUN directive is generically referred to as a port.

The <process_ref> is the name of a process that has been declared in a PROCESS directive. If the name denotes an array of processes, a subscript may be used to select a single process instance, a range of process instances, or a process instance relative to other instances.

The relative notation “[! + integer]” or “[! - integer]” is used in conjunction with a range of process instances. The “!” is used in the second process reference and takes on each value in the range specified by the first process instance. This notation is useful for connecting processes in a systolic array. For an example of the use of this directive to declare and connect an array of processes, see Figure 4.

The <fifo_spec> is used to set the size of the FIFOs at the sender and receiver respectively. If omitted, 16-element FIFOs are used.

(I): the connections between processes must be one-to-one. Broadcast patterns are not supported. Many to one connections are not supported.

In this example there are two software processes called setup and finish, and 10 instances of a hardware process p. The first instance of p receives stream data from setup. Instances 1 through 9 receive data from the previous instance. The ninth instance outputs data to the finish process.

4. Predeclared Integer Data Types

Streams-C provides predefined unsigned and signed integer data types for selected bit lengths ranging from 1 to 128, as shown in Figure 5. The bit lengths we support are 1, 2, 4, 6, 8, 12, 16, 18, 20, 24, 32, 40, 48, 64, 128. A simple convention is used to name these predefined types. Signed types have the name **sc_int<bit_length>**. Unsigned types have the name **sc_uint<bit_length>**. Variables of these types may be used in a Streams-C program. A stream may have one of these Streams-C integer types as its data element type (see Section 5.2).

Example: **sc_int20** filter_coeff;

(I): Arrays must have base type that matches the memory to which the array is allocated. For example, if an array is allocated to an 8-bit on-chip RAM, then the base type of the (possibly multidimensional) array must have a size of 8 bits.

```

/// PROCESS_FUN setup_run
/// OUT_STREAM sc_uint4 data
/// PROCESS_FUN_BODY
... beginning of C code ...
/// PROCESS_FUN_END

/// PROCESS_FUN finish_run
/// IN_STREAM sc_uint4 processed_data
/// PROCESS_FUN_BODY
... beginning of C code ...
/// PROCESS_FUN_END

/// PROCESS_FUN p_run
/// IN_STREAM str1 sc_uint4
/// OUT_S sc_uint8 str2
/// PROCESS_FUN_BODY
... beginning of C code ...
/// PROCESS_FUN_END

/// PROCESS setup PROCESS_FUN setup_run

/// PROCESS p [10] PROCESS_FUN p_run TYPE HP

/// PROCESS finish PROCESS_FUN finish_run

/// CONNECT p[0].str1 setup.data
/// CONNECT p[1 .. 9].str1 p[!-1].str2
/// CONNECT p[9].str2      finish.processed_data

```

Figure 4. CONNECT Directives Example

Signed	Unsigned
	sc_uint1
sc_int2	sc_uint2
sc_int4	sc_uint4
sc_int6	sc_uint6
sc_int8	sc_uint8
sc_int12	sc_uint12
sc_int16	sc_uint16
sc_int18	sc_uint18
sc_int20	sc_uint20
sc_int24	sc_uint24
sc_int32	sc_uint32
sc_int40	sc_uint40
sc_int48	sc_uint48
sc_int64	sc_uint64
sc_int128	sc_uint128

Figure 5. Streams-C Data Types

Return Type	Name	Arg 1	Arg 2	Arg 3	Arg 4
void	sc_initiate	(qualified) name	location	parameters	
void	sc_terminate	(qualified) name			
void	sc_stream_open	name			
void	sc_stream_close	name			
sc_error_type	sc_error	name			
Boolean	sc_stream_eos	name			
Int type	sc_stream_read	name			
void	sc_stream_write	name	value		
<sc_int_type>	sc_wait	name	name ...		
void	sc_post	name	value		
<sc_int_type>	sc_bit_extract	value	start bit	number of bits	
void	sc_bit_insert	destination	dest start bit	number of bits	source
int	sc_my_id				

Figure 6. Streams-C Intrinsic Functions

5. Intrinsic Functions

Streams-C includes several predefined intrinsic functions. There are intrinsic functions related to process, stream and signal operations and those related to bit manipulation. The process functions allow you to initiate and destroy processes. The stream functions allow you to open, close, read, and write streams and check for the end of a stream as well as the error indicator. The signal functions allow you to post an event and wait for an event. The bit manipulation functions allow you to insert and extract bits. The predefined intrinsic functions are tabulated in Figure 6 and described below.

5.1. Functions to Manage Processes

There are three functions provided to manage processes. Processes are defined using the directives outlined in Section 3.2. A process object begins execution after the **sc_initiate** function is called. The process name is the first parameter to the function. Optionally, a specific instance of an array process may be specified with an array reference. If the process name is that of an array of processes, and the array reference is omitted, the entire array is initiated. The remaining parameter is the argument to the process(es).

The intrinsic function **sc_terminate** closes down a process, process instance, or range of processes.

The **sc_my_id** function returns the process's id number. Each process has a unique id number starting at 1.

(I) Id numbers are assigned in the order that processes are declared in the .sc file.

sc_initiate(<process_name> ['[' <integer>']'] [, <process_parameters>])

sc_terminate(<process_name>, <integer>)

sc_my_id ()

The initiate and terminate intrinsic functions may only be called from the C “main” or from other software processes. They may not be called from hardware processes. *in the future for SlaacIV we can relax that restriction.*

5.2. Stream Processing Functions

The first operation to be performed on a stream is the stream open. Since a stream formal parameter to a process must be either input or output, it is not necessary in a stream open function call to specify a direction (unlike file I/O):

sc_stream_open(<stream_name>)

The stream open resets the stream internal state. There are no error conditions associated with a stream open.

When the stream is no longer needed, it may be closed:

sc_stream_close(<stream_name>)

The stream close writes an “end-of-stream” token to the output stream. There are no error conditions associated with a stream close.

Some stream operations might result in an error. To check for an error on a stream, the **sc_error** function may be called:

sc_error_type sc_error(<stream_name>)

(I): Currently only one error is defined: overflow, which is 1. No error is a zero.

On an input stream, two additional operations may be performed: end-of-stream test and stream read. The end-of-stream test checks to see whether a “close” operation was performed on the stream by the stream writer. It does this by checking the current element at the head of the stream. If this element is the distinguished “end-of-stream” token, a “true” value is returned; otherwise a “false” value is returned.

The stream read tries to read the next stream element, and blocks if the stream is empty. A read operation on a closed stream returns zero and sets the end-of-stream flag. Thus the correct sequence of operations is to do an initial stream read followed by a loop conditional on the end-of-stream condition.

Boolean sc_stream_eos(<stream_name>)

This operation is only allowed on input streams.

<sc_[u]int_type> sc_stream_read(<stream_name>)

This function returns a stream element of the Streams-C integer data type associated with the stream (see Section 4 for a list of Streams-C integer data types). If the stream is closed, zero is returned, and a subsequent call to **sc_stream_eos** returns True. If an error was encountered, a subsequent call to **sc_error(<stream_name>)** returns the error and clears the error indicator. The stream read function is only allowed on input streams.

Output streams may be written:

sc_stream_write(<stream_name>, <value>)

The stream must be a writable stream, and the value must be coercible to the stream data type.

5.3. Signal Functions

Signals are used for directed occasional communication between processes, typically for synchronization. Two operations are permitted on signals: post and wait. A parameter may be passed with the signal.

<sc_int_type> sc_wait(<signal_name_list>)

The process receives a signal posted by the signal writer. If a signal has not yet been posted, the process waits. If the wait statement specifies more than one signal, the statement returns whenever one of the signals in the list has been posted.

sc_post(<signal_name>, <value>)

The signal is posted along with the parameter, over-writing any previously posted signals. The process continues immediately. If acknowledgement is desired, the receiving process should post a different signal back to the sender, and the sender should wait for the acknowledging signal.

5.4. Bit Manipulation Functions

There are two functions that are useful for bit manipulation: extracting bits and inserting bits. For both these functions, the start bit is the low order bit and the number of bits counts from the low order bit.

<sc_int_type> sc_bit_extract(<value>, <start_bit>, <number_of_bits>)

This function returns a contiguous range of bits extracted from **<value>**, starting at the specified start bit for the specified number of bits. *do we coerce to the next largest ‘sc’ type or create a new type of exactly the right size?*

sc_bit_insert(<destination>, <d_start_bit>, <number_of_bits>, <source>)

The source is inserted into the destination starting at bit **<d_start_bit>** for **<number_of_bits>**. Truncation or sign extension are performed depending on the underlying data type. The source is an expression, and may itself be a bit extract operation.

5.5. Miscellaneous Constructs

The IF_SIM macro is provided for convenience. The body of the macro is executed in simulation mode and omitted in synthesis mode. A corresponding IN_NSIM macro is provided to include code for synthesis but not simulation.

Another convenient construct is the **/// HARDWARE INCLUDE /// END HARDWARE INCLUDE** block. This block is used to name include files that must be included for synthesis. Most include files such as stdio.h or math.h are not included with the input to the synthesis compiler. Putting include files into the hardware include block ensures that those files will get included in the synthesis compile.

6. Hardware-Supported Subset of C

- Dynamic memory allocation is not supported
- Pointers are not permitted. Indirect reference is done through array reference.

7. Style Issues

7.1. Optimization Hints

7.2. Simulation vs. Synthesis

Occasionally it is useful to write the code in one way for simulation and slightly different for synthesis. The IF_SIM macro is provided for this purpose.

We have found that C compiler bugs sometimes cause large locally allocated arrays to get corrupted. Thus to circumvent the bug in simulation, the array is globally allocated during simulation and locally allocated for synthesis.

8. Using sc2

8.1. Compiler Organization

A Streams-C program may be simulated at the functional level (see figure 7). Our functional simulator uses the Linux pthreads package to support concurrent processes and stream communication. At this level, the programmer can use conventional software debuggers and “print” statements to understand the parallel program’s concurrency behavior. The programmer can detect many potential deadlock and livelock conditions, and get a good approximation for buffer sizes required for correct program execution.

Our simulation tools use the `///` annotations to generate a C++ program that links the process function body with the simulation library. The generated C++ source program is then linked with our “ptstreams” library to produce a Linux executable that can run on the Linux workstation. The process of compiling for simulation is described in greater detail in Section 8.2.

When the program is compiled for synthesis, there are both software and hardware “object” files generated. The software executable contains all software processes as well as the runtime system to communicate with hardware processes. The hardware bit stream(s) contain all the hardware processes as well as the hardware libraries for stream communication and sequence control. Compiling for synthesis is described in greater detail in Section 8.3.

Note: A pre-processor converts the .sc file into C++ or C for the simulation or synthesis process respectively. The pre-processor parses only the “///” directives, and does not detect syntax errors in the user’s code. Thus you should expect to get error messages from the C++ or sc2 synthesis compiler relative to the generated code.

8.2. How to compile for simulation

8.3. How to compile for synthesis

To compile a `<program_name>.sc` file for synthesis, use the standard Streams-C makefile with a target of `<program_name>.vhd`.
Need to figure out how to specify different FPGA boards to the makefile.

how to go from .vhd to .x86

There are numerous phases and intermediate files created on the path from .sc to the .vhd output. Any of the intermediate targets may be specified as a target, if desired.

1. .sc → .cf converts the “///” annotations into C pragmas for the synthesis compiler
2. .cf → .snt applies the SUIF snoot C parser (as modified for Streams-C)
3. .snt → .spf applies numerous porky passes to eventually generate an input file into the sc2 compiler passes.

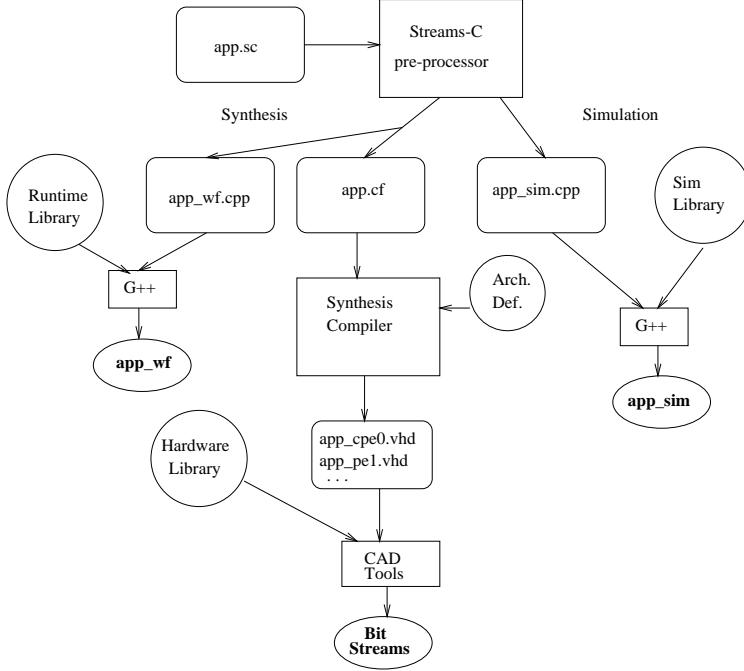


Figure 7. Organization of the Compiler

4. .spf → .spg performs the first sc2 pass to *normalize* the syntax tree and enforce the sc2 C subset.
5. .spg → .zsd is the major sc2 pass that *schedules* each hardware process. A porky pass is then applied to dismantle control structure.
6. .zsd → .vhd runs the *vhdl generator* over the scheduled SUIF representation.

Streams-C Pragma Format

When compiling for synthesis, a script converts each “`///`” block in the .sc file into a C pragma. The normal SUIF processing incorporates the pragmas into the syntax tree. The normalize, schedule and vhdl generator use the pragma information during translation. Each pragma is tagged with the keyword “SC” followed by the name of the option (PROCESS_FUN, PROCESS, or CONNECT) and the additional qualifiers applicable to each option. The pragma must be on a single line. The format of the PROCESS_FUN pragma is shown in Figure 8.

The PROCESS pragma is shown in Figure 9. Each clause is required. If there is a single process instance, the array-spec is written “ARRAY 1.” If no on_spec was given in the .sc, a default name FPGA is used. The default for software processes is sc_host.

The CONNECT pragma is shown in Figure 10. If the process name specifies an array of processes, a specific instance or a range may be chosen. The PORT refers to a stream or signal previously defined in a PROCESS_FUN pragma. The to_range uses the “!” symbol to denote all instances in the <from_range>, and the second to_range parameter may be a signed integer denoting an offset from the range.

Example

For the example program shown in Section 8.4, the following .cf directives are generated:

```
#pragma SC PROCESS_FUN host1_run OUT_STREAM int output_stream \
PARAM int iterations
```

```
#pragma SC PROCESS_FUN host2_run IN_STREAM int input_stream
```

```
#pragma SC PROCESS_FUN <function_name> [<stream_signal_list>] [<parameter>]

<stream_signal_list> ::= <stream_signal> [ <stream_signal> ... ]
<stream_signal>      ::= <instream> | <outstream> | <insignal> | <outsignal>

<instream>       ::= IN_STREAM <type_name> <stream_name>
<outstream>      ::= OUT_STREAM <type_name> <stream_name>
<insignal>       ::= IN_SIGNAL <type_name> <signal_name>
<outsignal>      ::= OUT_SIGNAL <type_name> <signal_name>

<parameter>      ::= PARAM <type_name> <parameter_name>
```

Figure 8. PROCESS_FUN Pragma

```
#pragma SC PROCESS <process_name> <array_spec> <process_fun_spec> \
<typespec> <on_spec>

<array_spec>     ::= ARRAY <int>
<process_fun_spec> ::= PROCESS_FUN <name>
<type_spec>      ::= TYPE HP|SP
<on_spec>        ::= ON <resource_name>
```

Figure 9. PROCESS Pragma

```
#pragma SC CONNECT <process_name> <from_spec> <port_spec> <fifo_spec> \
    TO <process_name> <to_spec> <port_spec> <fifo_spec>

<from_spec>      ::= INSTANCE <int> | <from_range>
<from_range>      ::= RANGE <int> <int>

<port_spec>       ::= PORT <name>

<to_spec>         ::= INSTANCE <int> | <to_range>
<to_range>         ::= RANGE ! <int>

<fifo_spec>       ::= FIFO_SIZE <uint>
```

Figure 10. CONNECT Pragma

```

#pragma SC PROCESS_FUN controller_run IN_STREAM int input_stream \
OUT_STREAM int output_stream

#pragma SC PROCESS_FUN pe1_proc_run IN_STREAM int input_stream \
OUT_STREAM int output_stream

#pragma SC PROCESS host1 ARRAY 1 PROCESS_FUN host1_run TYPE SP\
ON wfhost

#pragma SC PROCESS host2 ARRAY 1 PROCESS_FUN host2_run TYPE SP\
ON wfhost

#pragma SC PROCESS controller ARRAY 1 PROCESS_FUN controller_run \
ON wfb0pe0

#pragma SC PROCESS ctrlr_pe1_p ARRAY 1 PROCESS_FUN pe1_proc_run \
ON wf_b0pe1

#pragma SC CONNECT host1 INSTANCE 0 PORT output_stream TO controller
INSTANCE 0 input_stream

#pragma SC CONNECT controller INSTANCE 0 PORT output_stream TO ctrlr_pe1_p
INSTANCE 0 input_stream

#pragma SC CONNECT ctrlr_pe1_p INSTANCE 0 PORT output_stream TO host2
INSTANCE 0 input_stream

```

8.4. Examples

This section contains several Streams-C examples. The first example is a simple pass-through pipeline and illustrates how to define processes and streams, and how to use the stream intrinsics.

more examples: sc_hpce, ppf, kmeans, ppi

8.4.1 Example 1: Passing Data in a Pipeline

This program strm.sc has two software processes and two hardware processes, as shown in Figure 11. The first software process host1, with run function host1_run opens an output stream and writes a sequence of integers to the stream. The bound on the loop (“iterations”) is set by the input argument to the program invocation (eg. the invocation “strm 400” causes a sequence of integers from 0 to 399 to be written to the output stream).

The stream sent by host1 goes to a hardware process controller with run function controller_run. This process simply forwards the stream to the next hardware process, ctrlr_pe1_p.

(I): Note the use of a pipelining pragma in the while loop of process controller. The current version of the compiler automatically pipelines for loops, but only pipelines while loops when there is a pipeline pragma.

ctrlr_pe1_p has two phases. First it copies its input stream to memory. When the whole stream has been read into memory, it reads back the data in reverse order and writes to its output stream.

The final process, host2, using run function host2_run, reads the stream from ctrlr_pe1_p and prints out the data received from the stream.

The main program parses the input parameter and then initiates all the processes. A terminate is not necessary, as the processes terminate upon exit from the run function.

The IF_SIM macro is provided for convenience. The body of the macro is executed in simulation mode and omitted in synthesis mode.

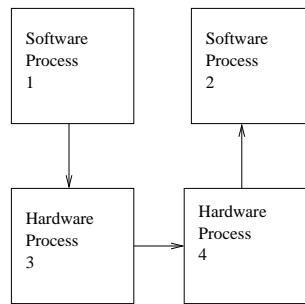


Figure 11. Process interconnection for Example 1

```

/*
 * Example streams-c test program
 * Algorithm:
 *   read from an input stream to CPE0,
 *   write stream element to PE1.
 *   in PE1, write to memory,
 *   at end of stream, read from memory and
 *   write to output fifo
 *
 *   tests stream modules, pipeline modules, memory interface
 */

```

```

#include <stdio.h>

float freq = SC_WF_DEFAULT_CLK_FREQ;

#define MAX 5000

void usage(char* ProgramName)
{
    printf("USAGE: %s <# iterations> (%d is default, max is %d)\n",
ProgramName, iterations, MAX);
}

int parse_input_pars(int argc, char **argv)
{
    char* ProgramName;

    ProgramName = argv [0];

    IF_SIM(printf("StreamC Memory test\n"));

    if(argc == 2) {
        int i;
        int iterations = MAX;

        sscanf(argv[1], "%i", &i);
    }
}

```

```

if (( i>=0) && (i<=MAX))
    iterations = i;
else usage(ProgramName);
} else if (argc != 1)
    usage(ProgramName);
return iterations;
}

/// PROCESS_FUN host1_run
/// OUT_STREAM int output_stream
/// PARAM int iterations
/// PROCESS_FUN_BODY

int i;

printf("Process host1 entered\n");
sc_stream_open(output_stream);

printf("Process host1 opened stream: output_stream\n");

for(i=0; i<iterations; i++) {
    printf("Process host1 writing stream: output_stream with: %x\n", i);
    sc_stream_write(output_stream, i);
}

printf("Prcess host1 Closing stream output_stream\n");

sc_stream_close(output_stream);

printf("Process host1 exiting\n");

/// PROCESS_FUN_END

/// PROCESS_FUN host2_run
/// IN_STREAM int input_stream
/// PROCESS_FUN_BODY

int j;

printf("Process host2 entered\n");
sc_stream_open(input_stream);

printf("Process host2 opened stream: input_stream\n");

printf("Process host2 reading stream: input_stream\n");
j = sc_stream_read(input_stream);

while(!sc_stream_eos(input_stream)) {
    printf("Process host2 read %x from stream: input_stream\n", j);
}

```

```

        j = sc_stream_read(input_stream);
    }

printf("Process host2 Closing stream input_stream\n");
sc_stream_close(input_stream);

printf("Process host2 exiting\n");

/// PROCESS_FUN_END

/// PROCESS_FUN controller_run
/// IN_STREAM int input_stream
/// OUT_STREAM int output_stream
/// PROCESS_FUN_BODY

int i;

IF_SIM(sprintf("Process controller entered\n"));

sc_stream_open(input_stream);
IF_SIM(sprintf("Process controller opened stream: input_stream\n"));

sc_stream_open(output_stream);
IF_SIM(sprintf("Process controller opened stream: output_stream\n"));

i = sc_stream_read(input_stream);

while(!sc_stream_eos(input_stream)) {
#pragma SC2 pipeline
    sc_stream_write(output_stream, i);
    i = sc_stream_read(input_stream);
}

IF_SIM(sprintf("Process controller Closing stream input_stream\n"));
sc_stream_close(input_stream);

IF_SIM(sprintf("Process controller Closing stream output_stream\n"));
sc_stream_close(output_stream);

IF_SIM(sprintf("Process controller exiting\n"));

/// PROCESS_FUN_END

/// PROCESS_FUN pel_proc_run
/// IN_STREAM int input_stream
/// OUT_STREAM int output_stream
/// PROCESS_FUN_BODY

int i, il;
int odata;
int A[5000];

```

```

IF_SIM(sprintf("Process pel_proc entered\n"));

sc_stream_open(input_stream);
IF_SIM(sprintf("Process pel_proc opened stream: input_stream\n"));

sc_stream_open(output_stream);
IF_SIM(sprintf("Process pel_proc opened stream: output_stream\n"));

i1 = sc_stream_read(input_stream);
i = 0;
while(! sc_stream_eos(input_stream)) {
#pragma SC2 pipeline
    A[i] = i1;
    i1 = sc_stream_read(input_stream);
    i++; /* max of 5000 is enforced at host */
}

for (i=i; i>=0; i--) {
#pragma SC2 pipeline
    sc_stream_write(output_stream, A[i]);
}

IF_SIM(sprintf("Process pel_proc Closing stream input_stream\n"));
sc_stream_close(input_stream);

IF_SIM(sprintf("Process pel_proc Closing stream output_stream\n"));
sc_stream_close(output_stream);

IF_SIM(sprintf("Process pel_proc exiting\n"));

/// PROCESS_FUN_END

// 
// process definitions
//

/// PROCESS controller PROCESS_FUN controller_run TYPE HP ON wf_b0pe0

/// PROCESS ctlr_pel_p PROCESS_FUN pel_proc_run TYPE HP ON wf_b0pe1

/// PROCESS host1 PROCESS_FUN host1_run

/// PROCESS host2 PROCESS_FUN host2_run

// 
// connections
//

/// CONNECT host1.output_stream controller.input_stream
/// CONNECT controller.output_stream ctlr_pel_p.input_stream
/// CONNECT ctlr_pel_p.output_stream host2.input_stream

```

```

void main(int argc, char *argv[]) {
    int iterations = parse_input_pars(argv, argc);
    sc_initiate(host2);
    sc_initiate(controller);
    sc_initiate(ctlr_pel_p);
    sc_initiate(host1, iterations);
}

```

9. Compiler Implementation Notes

References

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